

CSE423: Embedded Systems

Summer, 2020

Introduction to Embedded Systems





Today's Lecture

- ❑ What is the embedded system?
- ❑ Characteristic and application of Embedded Systems
- ❑ Use of micro-processor in embedded systems

What is Embedded Systems?



- **Definition:** An Embedded system is a microprocessor-based computer hardware system with software that is designed to perform a dedicated function, either as an independent system or as a part of a large system. At the core is an integrated circuit designed to carry out computation for real-time operations.

Embedded Systems (Contd.)

- ▶ We are surrounded by Embedded Systems.
 - ▶ Cell Phones
 - ▶ Automatic Washing Machines.
 - ▶ Traffic Signals with Timers.
 - ▶ Automobile Electronics.



- ▶ Find a system that contains no electronic system.
- ▶ How can a electronic system improve the functionality/efficiency of that system.
- ▶ Custom design an embedded system for the same.

Embedded Systems (contd.)

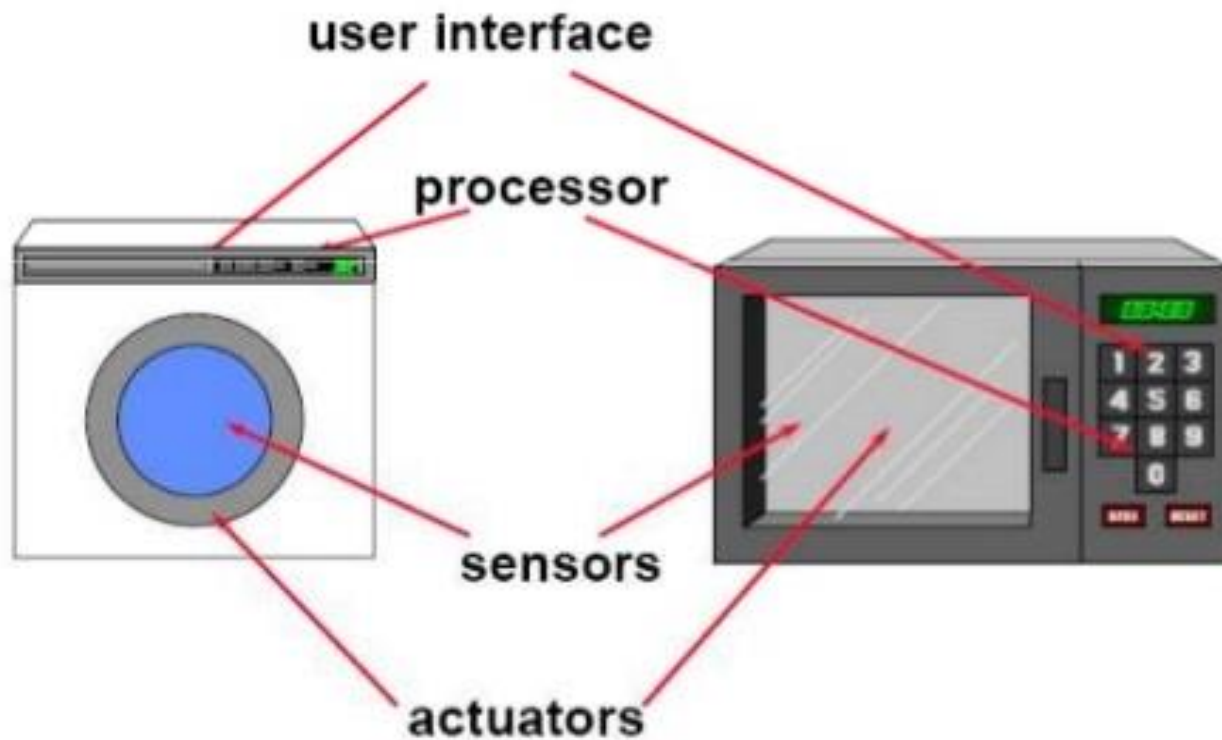
- ▶ Embedded system means the processor is embedded into that application.
- ▶ An embedded product uses a microprocessor or microcontroller to do one task only.
- ▶ In an embedded system, there is only one application software that is typically burned into ROM.
- ▶ Example : printer, keyboard, video game player



Embedded Systems (contd.)



Consumer electronics, for example MP3 Audio, digital camera, home electronics,



Characteristics of Embedded Systems

- The system must meet the following characteristics:
 - Performance
 - Cost/size
 - Real time requirements
 - Power consumption
 - Reliability



Characteristics of Embedded Systems

- ▶ Must be *efficient*:
 - *Energy* efficient
 - *Code-size* efficient (especially for systems on a chip)
 - *Run-time* efficient
 - *Weight* efficient
 - *Cost* efficient
- ▶ *Dedicated* towards a certain *application*: Knowledge about behavior at design time can be used to minimize resources and to maximize robustness.
- ▶ *Dedicated* user *interface* (no mouse, keyboard and screen).



Characteristics of Embedded Systems

- ▶ Many ES must meet *real-time constraints*:
 - A real-time system must *react to stimuli* from the controlled object (or the operator) within the time interval dictated by the environment.
 - For real-time systems, right answers arriving too late (or even too early) are wrong.

„A real-time constraint is called hard, if not meeting that constraint could result in a catastrophe“ [Kopetz, 1997].

- All other time-constraints are called soft.
- A *guaranteed system response* has to be explained without statistical arguments.



Characteristics of Embedded Systems

- ▶ Frequently *connected to physical environment* through sensors and actuators,
- ▶ *Hybrid systems* (analog + digital parts).
- ▶ Typically, ES are *reactive systems*:

„A reactive system is one which is in continual interaction with its environment and executes at a pace determined by that environment“ [Bergé, 1995]

- Behavior depends on input and current state.
 - ☞ automata model often appropriate,



Characteristics of Embedded Systems

▶ Embedded Systems

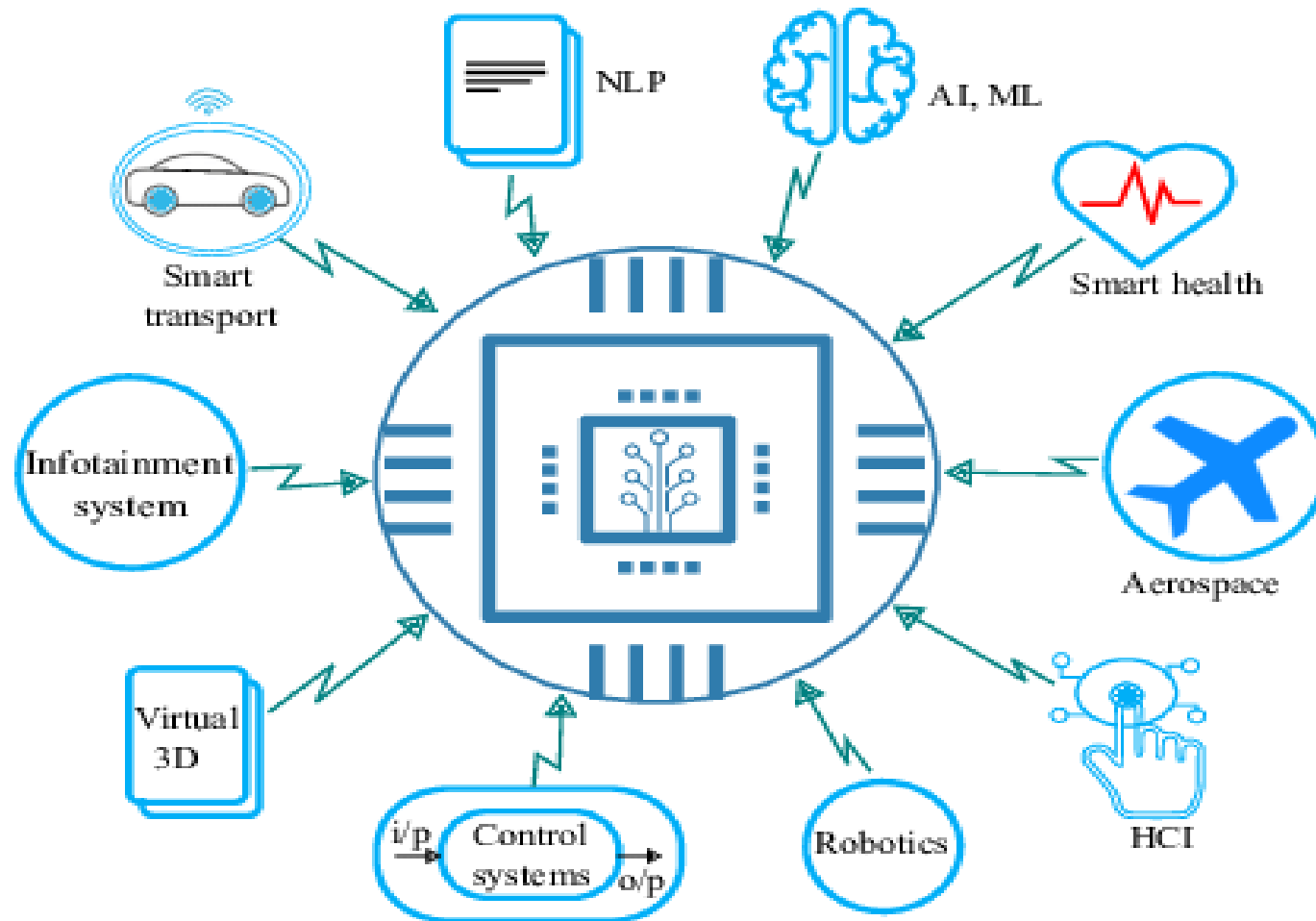
- Few applications that are known at design-time.
- Not programmable by end user.
- Fixed run-time requirements (additional computing power not useful).
- Criteria:
 - cost
 - power consumption
 - predictability

▶ General Purpose Computing

- Broad class of applications.
- Programmable by end user.
- Faster is better.
- Criteria:
 - cost
 - average speed



Current Domain of Embedded Systems



Components of Embedded Systems

- Analog Components
 - Sensors, Actuators, Controllers, ...
- Digital Components
 - Processor, Coprocessors
 - Memories
 - Controllers, Buses
 - Application Specific Integrated Circuits (ASIC)
- Converters – A2D, D2A, ...
- Software
 - Application Programs
 - Exception Handlers



Microprocessors in Embedded Systems?

- ❑ Alternatives: field-programmable gate arrays (FPGAs), custom logic, application specific integrated circuit (ASIC), etc.
- ❑ Microprocessors are often very efficient: can use same logic to perform many different functions.
- ❑ Microprocessors simplify the design of families of products.





Why Use Microprocessors?

- Two factors that work together to make microprocessor-based designs fast
 - First, microprocessors execute programs very efficiently. While there is overhead that must be paid for interpreting instructions, it can often be hidden by clever utilization of parallelism within the CPU
 - Second, microprocessor manufacturers spend a great deal of money to make their CPUs run very fast.



Why Use Microprocessors?

- Performance
 - Microprocessors use much more logic to implement a function than does custom logic.
 - But microprocessors are often at least as fast:
 - heavily pipelined;
 - large design teams;
 - aggressive VLSI technology.
- Power consumption
 - Custom logic is a clear winner for low power devices.
 - Modern microprocessors offer features to help control power consumption.
 - Software design techniques can help reduce power consumption.
- Heterogeneous systems: some custom logic for well-defined functions, CPUs+ software for everything else.



Microprocessor Varieties

- ❑ **Microcontroller:** includes I/O devices, on-board memory.
- ❑ **Digital signal processor (DSP):** microprocessor optimized for digital signal processing.
- ❑ Typical embedded word sizes: 8-bit, 16-bit, 32-bit.



Microprocessor Varieties

- 4-bit, 8-bit, 16-bit, 32-bit :
 - 8-bit processor : more than 3 billion new chips per year
 - 32-bit microprocessors : **PowerPC**, **68k**, **MIPS**, and **ARM** chips.
 - **ARM-based chips** alone do about **triple the volume** that Intel and AMD peddle to PC makers.
- Most (**98%** or so) 32-bit processors are used in embedded systems, not PCs.
- RISC-type processor owns most of the overall embedded market [MPF: 2002].



Platforms

- ❑ Embedded computing platform: hardware architecture + associated software.
- ❑ Many platforms are multiprocessors.
- ❑ Examples:
 - Single-chip multiprocessors for cell phone baseband.
 - Automotive network + processors.

The physics of software



- ❑ Computing is a physical act.
 - Software doesn't do anything without hardware.
- ❑ Executing software consumes energy, requires time.
- ❑ To understand the dynamics of software (time, energy), we need to characterize the platform on which the software runs.

Challenges in Embedded Computing System Design



- How much hardware do we need?
- How do we meet deadlines?
- How do we minimize power consumption?
- How do we design for upgradability?
- Does it really work?

What does “Performance” mean?



- In general-purpose computing, performance often means average-case, may not be well-defined.
- In real-time systems, performance means meeting deadlines.
 - Missing the deadline by even a little is bad.
 - Finishing ahead of the deadline may not help.

Characterizing performance



- We need to analyze the system at several levels of abstraction to understand performance:
 - CPU: microprocessor architecture.
 - Platform: bus, I/O devices.
 - Program: implementation, structure.
 - Task: multitasking, interaction between tasks.
 - Multiprocessor: interaction between processors.

Characteristics of Embedded Systems

- ❑ Very high performance, sophisticated functionality
 - Vision + compression + speech + networking all on the same platform.
- ❑ Multiple task, heterogeneous.
- ❑ Real-time.
- ❑ Often low power.
- ❑ Low manufacturing cost..
- ❑ Highly reliable.
 - I reboot my piano every 4 months, my PC every day.
- ❑ Designed to tight deadlines by small teams.



Functional Complexity



- Often have to run sophisticated algorithms or multiple algorithms.
 - Cell phone, laser printer.
- Often provide sophisticated user interfaces.

Design methodologies



- ❑ A procedure for designing a system.
- ❑ Understanding your methodology helps you ensure you didn't skip anything.
- ❑ Compilers, software engineering tools, computer-aided design (CAD) tools, etc., can be used to:
 - help automate methodology steps;
 - keep track of the methodology itself.

Levels of abstraction



requirements

specification

architecture

component
design

system
integration

Our requirements form



name

purpose

inputs

outputs

functions

performance

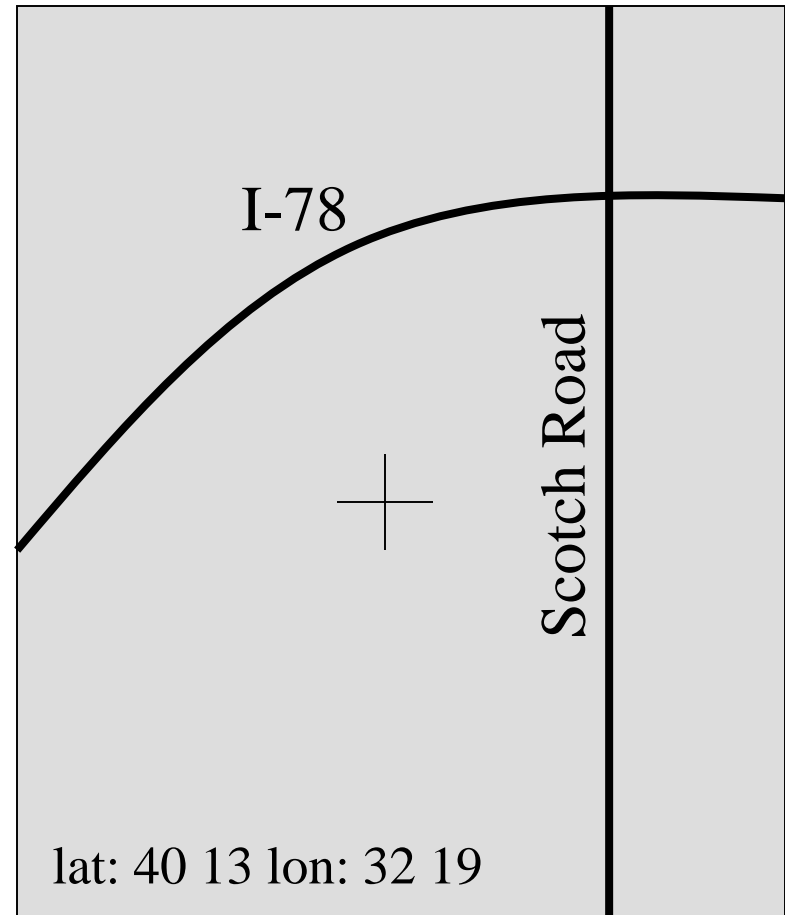
manufacturing cost

power

physical size/weight

Example: GPS moving map requirements

- Moving map obtains position from GPS, paints map from local database.



GPS moving map needs



- ❑ **Functionality:** For automotive use. Show major roads and landmarks.
- ❑ **User interface:** At least 400 x 600 pixel screen. Three buttons max. Pop-up menu.
- ❑ **Performance:** Map should scroll smoothly. No more than 1 sec power-up. Lock onto GPS within 15 seconds.
- ❑ **Cost:** \$120 street price = approx. \$30 cost of goods sold.

GPS moving map needs, cont'd.



- ❑ **Physical size/weight:** Should fit in hand.
- ❑ **Power consumption:** Should run for 8 hours on four AA batteries.

GPS moving map requirements form

name	GPS moving map
purpose	consumer-grade moving map for driving
inputs	power button, two control buttons
outputs	back-lit LCD 400 X 600
functions	5-receiver GPS; three resolutions; displays current lat/lon
performance	updates screen within 0.25 sec of movement
manufacturing cost	\$100 cost-of-goods-sold
power	100 mW
physical size/weight	no more than 2: X 6:, 12 oz.



Specification



- A more precise description of the system:
 - should not imply a particular architecture;
 - provides input to the architecture design process.
- May include functional and non-functional elements.
- May be executable or may be in mathematical form for proofs.

GPS specification



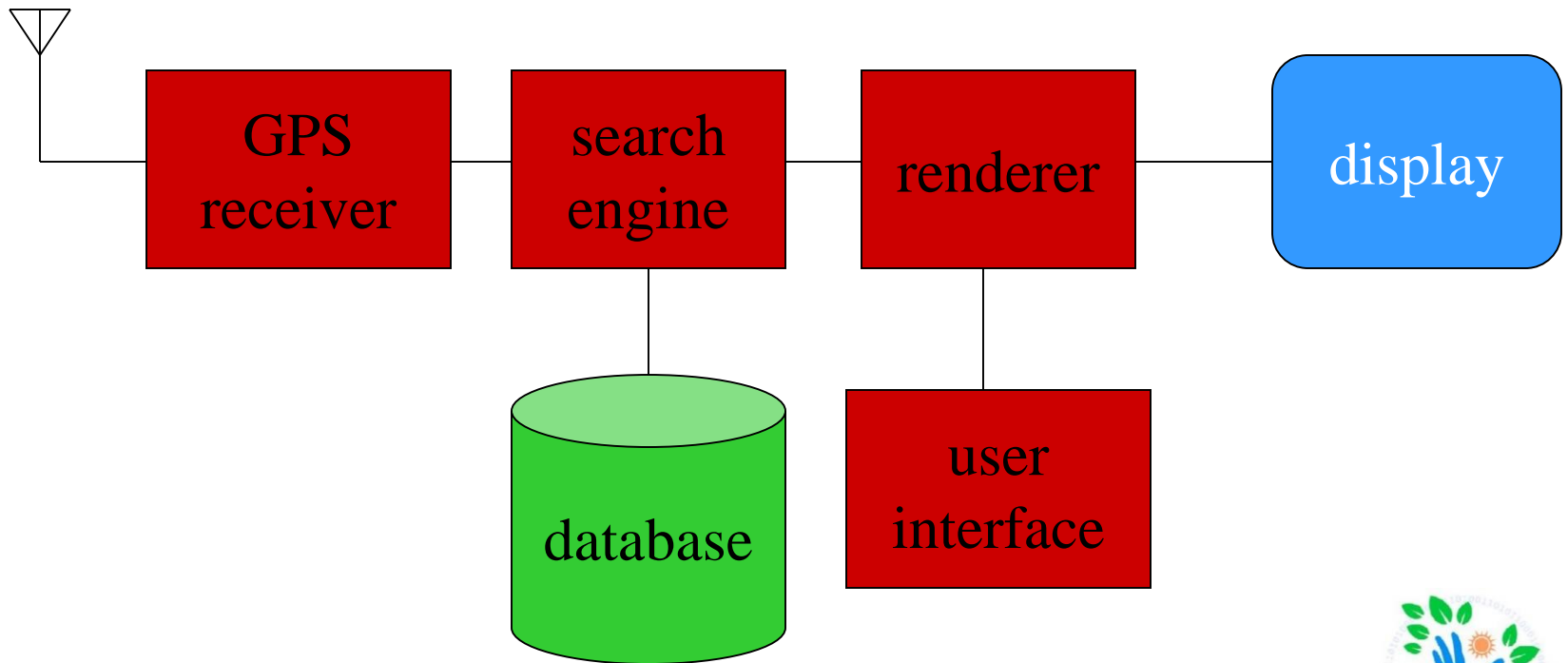
- Should include:
 - What is received from GPS;
 - map data;
 - user interface;
 - operations required to satisfy user requests;
 - background operations needed to keep the system running.

Architecture design

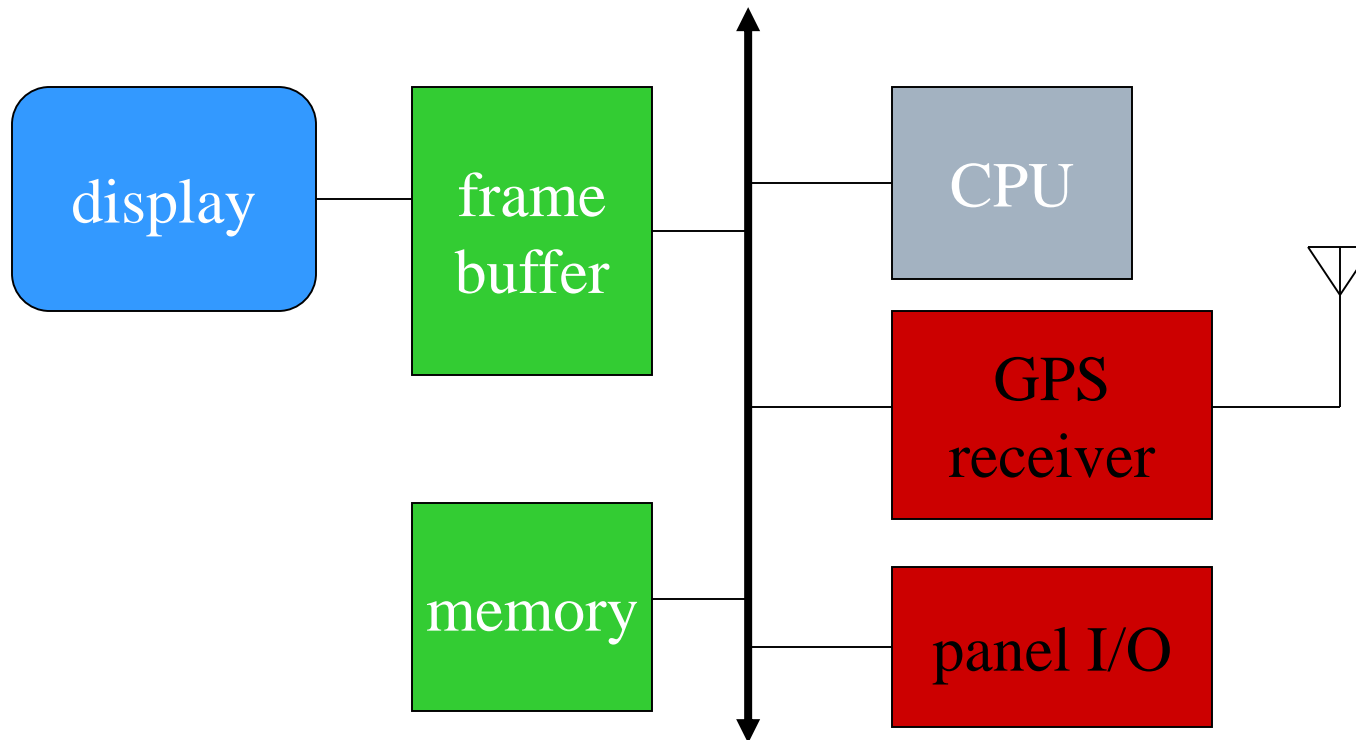


- ❑ What major components go satisfying the specification?
- ❑ Hardware components:
 - CPUs, peripherals, etc.
- ❑ Software components:
 - major programs and their operations.
- ❑ Must take into account functional and non-functional specifications.

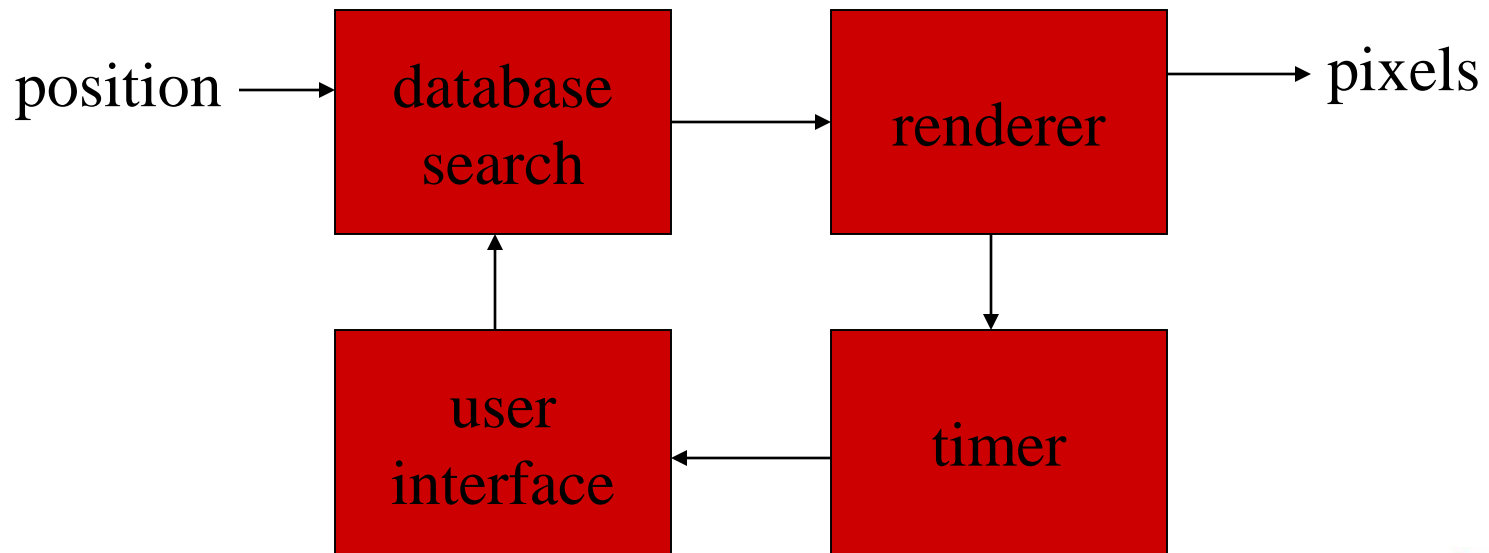
GPS moving map block diagram



GPS moving map hardware architecture



GPS moving map software architecture



Designing hardware and software components

- ❑ Must spend time architecting the system before you start coding.
- ❑ Some components are ready-made, some can be modified from existing designs, others must be designed from scratch.



System integration



- Put together the components.
 - Many bugs appear only at this stage.
- Have a plan for integrating components to uncover bugs quickly, test as much functionality as early as possible.

Summary



- ❑ Embedded computers are all around us.
 - Many systems have complex embedded hardware and software.
- ❑ Embedded systems pose many design challenges: design time, deadlines, power, etc.
- ❑ Design methodologies help us manage the design process.