Sinusoids and Phasors

EEE 101: "Basic Electrical Technology"

Civil Engineering Department

Spring 2021



Sinusoids

A sinusoid is a signal that has the form of the sine or cosine function.

Consider the sinusoidal voltage

$$v(t) = V_m \sin \omega t$$

where

 V_m = the *amplitude* of the sinusoid ω = the *angular frequency* in radians/s ωt = the *argument* of the sinusoid

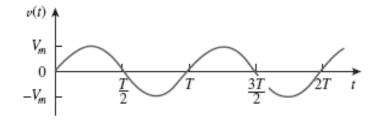
$$T = \frac{2\pi}{\omega}$$

$$v(t+T) = V_m \sin \omega (t+T) = V_m \sin \omega \left(t + \frac{2\pi}{\omega}\right)$$
$$= V_m \sin(\omega t + 2\pi) = V_m \sin \omega t = v(t)$$

Hence,

$$v(t + T) = v(t)$$
 A periodic function is one that satisfies $f(t) = f(t + nT)$, for all t and for all integers n.

be periodic. In general,



that is, v has the same value at t + T as it does at t and v(t) is said to

Sinusoids

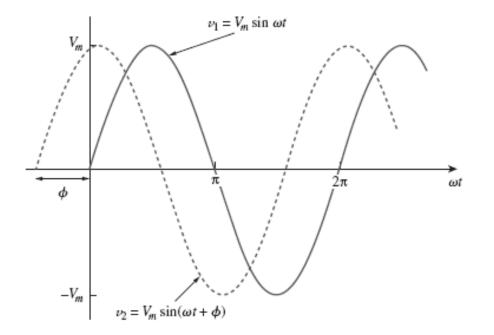
Let us now consider a more general expression for the sinusoid,

$$v(t) = V_m \sin(\omega t + \phi)$$

where $(\omega t + \phi)$ is the argument and ϕ is the *phase*. Both argument and phase can be in radians or degrees.

Let us examine the two sinusoids

 $v_1(t) = V_m \sin \omega t$ and $v_2(t) = V_m \sin(\omega t + \phi)$



Sinusoids

Find the amplitude, phase, period, and frequency of the sinusoid

$$v(t) = 12\cos(50t + 10^{\circ})$$

The amplitude is $V_m = 12$ V. The phase is $\phi = 10^{\circ}$. The angular frequency is $\omega = 50$ rad/s. The period $T = \frac{2\pi}{\omega} = \frac{2\pi}{50} = 0.1257$ s. The frequency is $f = \frac{1}{T} = 7.958$ Hz.

Calculate the phase angle between $v_1 = -10 \cos(\omega t + 50^\circ)$ and $v_2 =$ **Example 9.2** 12 $\sin(\omega t - 10^\circ)$. State which sinusoid is leading.

Sinusoids are easily expressed in terms of phasors, which are more convenient to work with than sine and cosine functions.

A phasor is a complex number that represents the amplitude and phase of a sinusoid.

A complex number z can be written in rectangular form as

$$z = x + jy$$

The complex number z can also be written in polar or exponential form as

$$z = r / \phi = r e^{j\phi}$$

where r is the magnitude of z, and ϕ is the phase of z. z can be represented in three ways:

$$z = x + jy$$
 Rectangular form
 $z = r / \phi$ Polar form
 $z = re^{j\phi}$ Exponential form

The relationship between the rectangular form and the polar form is shown in Fig. 9.6, where the x axis represents the real part and the y axis represents the imaginary part of a complex number. Given x and y, we can get r and ϕ as

$$r = \sqrt{x^2 + y^2}, \qquad \phi = \tan^{-1}\frac{y}{x}$$

On the other hand, if we know r and ϕ , we can obtain x and

$$x = r \cos \phi, \quad y = r \sin \phi$$

Thus, z may be written as

$$z = x + jy = r/\phi = r(\cos\phi + j\sin\phi)$$

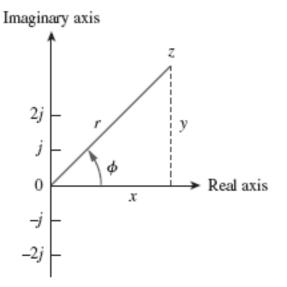


Figure 9.6 Representation of a complex number $z = x + jy = r / \phi$.

Addition and subtraction of complex numbers are better performed in rectangular form; multiplication and division are better done in polar form. Given the complex numbers

$$z = x + jy = r/\underline{\phi}, \qquad z_1 = x_1 + jy_1 = r_1/\underline{\phi}_1$$

 $z_2 = x_2 + jy_2 = r_2/\underline{\phi}_2$

the following operations are important. Addition:

$$z_1 + z_2 = (x_1 + x_2) + j(y_1 + y_2)$$
(9.18a)

Subtraction:

$$z_1 - z_2 = (x_1 - x_2) + j(y_1 - y_2)$$
 (9.18b)

Multiplication:

$$z_1 z_2 = r_1 r_2 / \phi_1 + \phi_2$$
 (9.18c)

Division:

$$\frac{z_1}{z_2} = \frac{r_1}{r_2} / \frac{\phi_1 - \phi_2}{\phi_1 - \phi_2}$$
(9.18d)

Reciprocal:

$$\frac{1}{z} = \frac{1}{r} / \underline{-\phi}$$
(9.18e)

Square Root:

$$\sqrt{z} = \sqrt{r} / \frac{\phi/2}{2}$$
(9.18f)

Complex Conjugate:

$$z^* = x - jy = r/-\phi = re^{-j\phi}$$
 (9.18g)

$$V = V_m e^{j\phi} = V_m / \phi$$

V is thus the *phasor representation* of the sinusoid v(t), as we said earlier. In other words, a phasor is a complex representation of the magnitude and phase of a sinusoid.

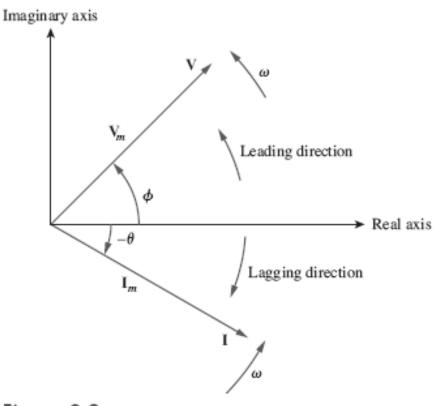


Figure 9.8 A phasor diagram showing $V = V_m / \phi$ and $I = I_m / -\theta$.

The differences between v(t) and V should be emphasized:

- v(t) is the instantaneous or time domain representation, while V is the frequency or phasor domain representation.
- v(t) is time dependent, while V is not. (This fact is often forgotten by students.)
- 3. v(t) is always real with no complex term, while V is generally complex.

Example 9.4	Transform these sinusoids to phasors:
	(a) $i = 6\cos(50t - 40^\circ)$ A
	(b) $v = -4\sin(30t + 50^\circ)$ V
	Solution:
	(a) $i = 6\cos(50t - 40^\circ)$ has the phasor
	$\mathbf{I} = 6 / -40^{\circ} \mathrm{A}$
	(b) Since $-\sin A = \cos(A + 90^{\circ})$,
	$v = -4\sin(30t + 50^\circ) = 4\cos(30t + 50^\circ + 90^\circ)$
	$= 4 \cos(30t + 140^{\circ}) V$
	The phasor form of v is
	$V = 4/140^{\circ} V$

Evaluate these complex numbers:

(a)
$$(40/50^{\circ} + 20/-30^{\circ})^{1/2}$$

(b) $\frac{10/-30^{\circ} + (3 - j4)}{(2 + j4)(3 - j5)^*}$

Solution:

(a) Using polar to rectangular transformation,

 $\begin{array}{l} 40\underline{/50^\circ} = 40(\cos 50^\circ + j\sin 50^\circ) = 25.71 + j30.64 \\ 20\underline{/-30^\circ} = 20[\cos(-30^\circ) + j\sin(-30^\circ)] = 17.32 - j10 \end{array}$

Adding them up gives

$$40/\underline{50^{\circ}} + 20/\underline{-30^{\circ}} = 43.03 + j20.64 = 47.72/25.63^{\circ}$$

Taking the square root of this,

$$(40/50^{\circ} + 20/-30^{\circ})^{1/2} = 6.91/12.81^{\circ}$$

(b) Using polar-rectangular transformation, addition, multiplication, and division,

$$\frac{10/-30^{\circ} + (3 - j4)}{(2 + j4)(3 - j5)^{*}} = \frac{8.66 - j5 + (3 - j4)}{(2 + j4)(3 + j5)}$$
$$= \frac{11.66 - j9}{-14 + j22} = \frac{14.73/-37.66^{\circ}}{26.08/122.47^{\circ}}$$
$$= 0.565/-160.13^{\circ}$$

Find the sinusoids represented by these phasors:

(a) I = -3 + j4 A(b) $V = j8e^{-j20^{\circ}} V$

Solution:

(a) $I = -3 + j4 = 5/(126.87^{\circ})$. Transforming this to the time domain gives

$$i(t) = 5 \cos(\omega t + 126.87^{\circ}) \text{ A}$$

(b) Since
$$j = 1/90^{\circ}$$
,
 $\mathbf{V} = j8/-20^{\circ} = (1/90^{\circ})(8/-20^{\circ})$
 $= 8/90^{\circ} - 20^{\circ} = 8/70^{\circ} \text{ V}$

Converting this to the time domain gives

$$v(t) = 8\cos(\omega t + 70^{\circ}) V$$

Given $i_1(t) = 4\cos(\omega t + 30^\circ)$ A and $i_2(t) = 5\sin(\omega t - 20^\circ)$ A, find their sum.

Solution:

Here is an important use of phasors—for summing sinusoids of the same frequency. Current $i_1(t)$ is in the standard form. Its phasor is

$$I_1 = 4/30^{\circ}$$

We need to express $i_2(t)$ in cosine form. The rule for converting sine to cosine is to subtract 90°. Hence,

$$i_2 = 5\cos(\omega t - 20^\circ - 90^\circ) = 5\cos(\omega t - 110^\circ)$$

and its phasor is

$$I_2 = 5/-110^{\circ}$$

If we let $i = i_1 + i_2$, then

$$\mathbf{I} = \mathbf{I}_1 + \mathbf{I}_2 = 4/30^\circ + 5/-110^\circ$$

= 3.464 + j2 - 1.71 - j4.698 = 1.754 - j2.698
= 3.218/-56.97° A

Phasor relationships for circuit elements

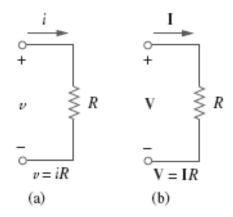
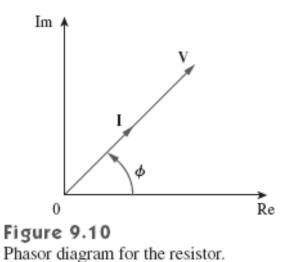
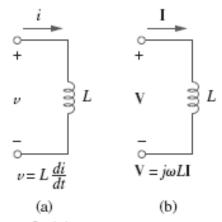


Figure 9.9

Voltage-current relations for a resistor in the: (a) time domain, (b) frequency domain.

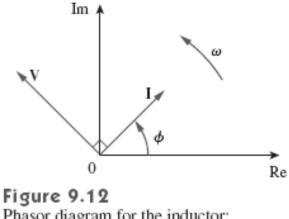


Phasor relationships for circuit elements





Voltage-current relations for an inductor in the: (a) time domain, (b) frequency domain.



Phasor diagram for the inductor; I lags V.

Phasor relationships for circuit elements

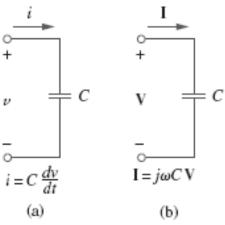


Figure 9.13

Voltage-current relations for a capacitor in the: (a) time domain, (b) frequency domain.

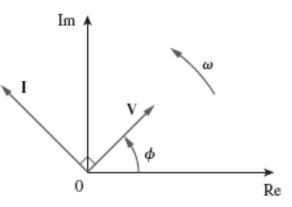


Figure 9.14 Phasor diagram for the capacitor; I leads V.

Example 9.8

The voltage $v = 12 \cos(60t + 45^\circ)$ is applied to a 0.1-H inductor. Find the steady-state current through the inductor.

Solution:

For the inductor, $V = j\omega LI$, where $\omega = 60 \text{ rad/s}$ and $V = 12/45^{\circ} V$. Hence,

$$\mathbf{I} = \frac{\mathbf{V}}{j\omega L} = \frac{12/45^{\circ}}{j60 \times 0.1} = \frac{12/45^{\circ}}{6/90^{\circ}} = 2/-45^{\circ} \,\mathrm{A}$$

Converting this to the time domain,

$$i(t) = 2\cos(60t - 45^\circ)$$
 A

The impedance **Z** of a circuit is the ratio of the phasor voltage **V** to the phasor current **I**, measured in ohms (Ω) .

$$Z = \frac{V}{I}$$
 or $V = ZI$

 $\mathbf{Z} = R + jX$ $\mathbf{Z} = |\mathbf{Z}| \underline{/\theta}$

$$\mathbf{Z} = R + jX = |\mathbf{Z}| / \underline{\theta}$$

where

$$|\mathbf{Z}| = \sqrt{R^2 + X^2}, \qquad \theta = \tan^{-1}\frac{X}{R}$$

and

$$R = |\mathbf{Z}|\cos\theta, \qquad X = |\mathbf{Z}|\sin\theta$$

The admittance \boldsymbol{Y} is the reciprocal of impedance, measured in siemens (S).

$$\mathbf{Y} = \frac{1}{\mathbf{Z}} = \frac{\mathbf{I}}{\mathbf{V}}$$

$$\mathbf{Y} = G + jB$$

$$G + jB = \frac{1}{R + jX}$$

Impedance and admittance

Find v(t) and i(t) in the circuit shown in Fig. 9.16.

Solution:

From the voltage source 10 cos 4t, $\omega = 4$,

$$V_s = 10/0^{\circ} V$$

The impedance is

$$\mathbf{Z} = 5 + \frac{1}{j\omega C} = 5 + \frac{1}{j4 \times 0.1} = 5 - j2.5 \ \Omega$$

Hence the current

$$\mathbf{I} = \frac{\mathbf{V}_s}{\mathbf{Z}} = \frac{10/\underline{0^\circ}}{5 - j2.5} = \frac{10(5 + j2.5)}{5^2 + 2.5^2}$$

= 1.6 + j0.8 = 1.789/26.57° A (9.9.1)

The voltage across the capacitor is

$$\mathbf{V} = \mathbf{I}\mathbf{Z}_{C} = \frac{\mathbf{I}}{j\omega C} = \frac{1.789/26.57^{\circ}}{j4 \times 0.1}$$
$$= \frac{1.789/26.57^{\circ}}{0.4/90^{\circ}} = 4.47/-63.43^{\circ} \,\mathrm{V}$$
(9.9.2)

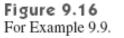
Converting I and V in Eqs. (9.9.1) and (9.9.2) to the time domain, we get

$$i(t) = 1.789 \cos(4t + 26.57^\circ) \text{ A}$$

 $v(t) = 4.47 \cos(4t - 63.43^\circ) \text{ V}$

Notice that i(t) leads v(t) by 90° as expected.

 $v_{t} = 10 \cos 4t$ $\stackrel{i}{=}$ 5Ω 0.1 F $\stackrel{+}{=}$ $\stackrel{v}{=}$



Kirchhoff's laws (KVL and KCL) in frequency domain

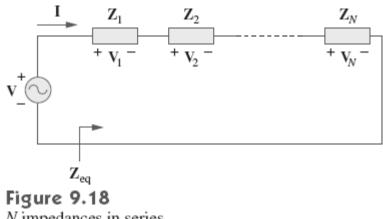
$$\mathbf{V}_1 + \mathbf{V}_2 + \dots + \mathbf{V}_n = \mathbf{0}$$

indicating that Kirchhoff's voltage law holds for phasors.

 $\mathbf{I}_1 + \mathbf{I}_2 + \dots + \mathbf{I}_n = \mathbf{0}$

which is Kirchhoff's current law in the frequency domain.

Once we have shown that both KVL and KCL hold in the frequency domain, it is easy to do many things, such as impedance combination, nodal and mesh analyses, superposition, and source transformation.



$$\mathbf{Z}_{\mathrm{eq}} = \mathbf{Z}_1 + \mathbf{Z}_2 + \dots + \mathbf{Z}_N$$

N impedances in series.

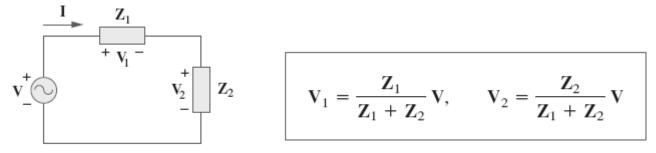
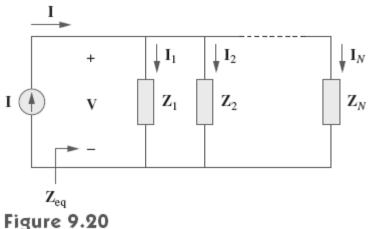


Figure 9.19 Voltage division.

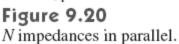


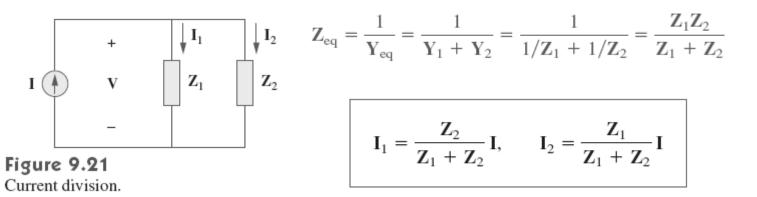
The equivalent impedance is

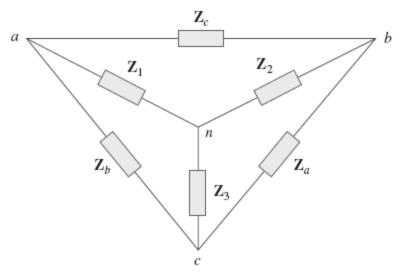
$$\frac{1}{Z_{eq}} = \frac{I}{V} = \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_N}$$

and the equivalent admittance is

$$\mathbf{Y}_{\mathrm{eq}} = \mathbf{Y}_1 + \mathbf{Y}_2 + \dots + \mathbf{Y}_N$$







Y- Δ Conversion:

 $\mathbf{Z}_{a} = \frac{\mathbf{Z}_{1}\mathbf{Z}_{2} + \mathbf{Z}_{2}\mathbf{Z}_{3} + \mathbf{Z}_{3}\mathbf{Z}_{1}}{\mathbf{Z}_{1}}$ $\mathbf{Z}_{b} = \frac{\mathbf{Z}_{1}\mathbf{Z}_{2} + \mathbf{Z}_{2}\mathbf{Z}_{3} + \mathbf{Z}_{3}\mathbf{Z}_{1}}{\mathbf{Z}_{2}}$ $\mathbf{Z}_{c} = \frac{\mathbf{Z}_{1}\mathbf{Z}_{2} + \mathbf{Z}_{2}\mathbf{Z}_{3} + \mathbf{Z}_{3}\mathbf{Z}_{1}}{\mathbf{Z}_{3}}$

 Δ -Y Conversion:

Figure 9.22 Superimposed *Y* and Δ networks.

A delta or wye circuit is said to be balanced if it has equal impedances in all three branches.

$$\mathbf{Z}_{\Delta} = 3\mathbf{Z}_{Y}$$
 or $\mathbf{Z}_{Y} = \frac{1}{3}\mathbf{Z}_{\Delta}$

where $\mathbf{Z}_Y = \mathbf{Z}_1 = \mathbf{Z}_2 = \mathbf{Z}_3$ and $\mathbf{Z}_{\Delta} = \mathbf{Z}_a = \mathbf{Z}_b = \mathbf{Z}_c$.

$$Z_1 = \frac{Z_b Z_c}{Z_a + Z_b + Z_c}$$
$$Z_2 = \frac{Z_c Z_a}{Z_a + Z_b + Z_c}$$
$$Z_3 = \frac{Z_a Z_b}{Z_a + Z_b + Z_c}$$

Find the input impedance of the circuit in Fig. 9.23. Assume that the circuit operates at $\omega = 50$ rad/s.

Solution:

Let

- Z_1 = Impedance of the 2-mF capacitor
- Z_2 = Impedance of the 3- Ω resistor in series with the10-mF capacitor
- Z_3 = Impedance of the 0.2-H inductor in series with the 8- Ω resistor

Then

$$Z_{1} = \frac{1}{j\omega C} = \frac{1}{j50 \times 2 \times 10^{-3}} = -j10 \Omega$$

$$Z_{2} = 3 + \frac{1}{j\omega C} = 3 + \frac{1}{j50 \times 10 \times 10^{-3}} = (3 - j2) \Omega$$

$$Z_{3} = 8 + j\omega L = 8 + j50 \times 0.2 = (8 + j10) \Omega$$

The input impedance is

$$Z_{in} = Z_1 + Z_2 || Z_3 = -j10 + \frac{(3 - j2)(8 + j10)}{11 + j8}$$
$$= -j10 + \frac{(44 + j14)(11 - j8)}{11^2 + 8^2} = -j10 + 3.22 - j1.07 \Omega$$

Thus,

$$Z_{in} = 3.22 - j11.07 \Omega$$

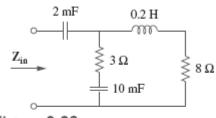
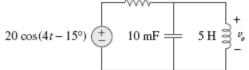


Figure 9.23 For Example 9.10.

Example 9.11

Determine $v_{\rho}(t)$ in the circuit of Fig. 9.25.

Solution



 60Ω

To do the analysis in the frequency domain, we must first transform the time domain circuit in Fig. 9.25 to the phasor domain equivalent in Fig. 9.26. The transformation produces

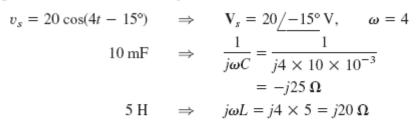
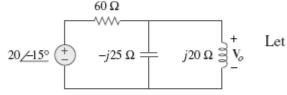


Figure 9.25 For Example 9.11.



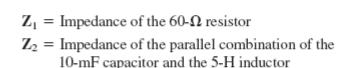


Figure 9.26 The frequency domain equivalent of the circuit in Fig. 9.25.

Then $Z_1 = 60 \Omega$ and

$$\mathbf{Z}_2 = -j25 \parallel j20 = \frac{-j25 \times j20}{-j25 + j20} = j100 \,\Omega$$

By the voltage-division principle,

$$\mathbf{V}_{o} = \frac{\mathbf{Z}_{2}}{\mathbf{Z}_{1} + \mathbf{Z}_{2}} \mathbf{V}_{s} = \frac{j100}{60 + j100} (20/-15^{\circ})$$
$$= (0.8575/30.96^{\circ})(20/-15^{\circ}) = 17.15/15.96^{\circ} \text{ V}$$

We convert this to the time domain and obtain

$$v_o(t) = 17.15 \cos(4t + 15.96^\circ) \text{ V}$$

Find current I in the circuit of Fig. 9.28.

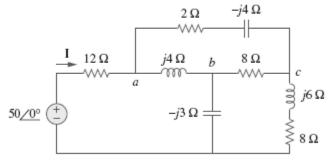


Figure 9.28 For Example 9.12.

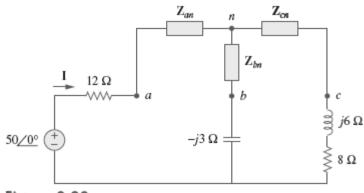


Figure 9.29 The circuit in Fig. 9.28 after delta-to-wye transformation.

Example 9.12

Solution:

The delta network connected to nodes a, b, and c can be converted to the Y network of Fig. 9.29. We obtain the Y impedances as follows using Eq. (9.68):

$$\mathbf{Z}_{an} = \frac{j4(2-j4)}{j4+2-j4+8} = \frac{4(4+j2)}{10} = (1.6+j0.8) \,\Omega$$
$$\mathbf{Z}_{bn} = \frac{j4(8)}{10} = j3.2 \,\Omega, \qquad \mathbf{Z}_{cn} = \frac{8(2-j4)}{10} = (1.6-j3.2) \,\Omega$$

The total impedance at the source terminals is

$$Z = 12 + Z_{cn} + (Z_{bn} - j3) \| (Z_{cn} + j6 + 8)$$

= 12 + 1.6 + j0.8 + (j0.2) || (9.6 + j2.8)
= 13.6 + j0.8 + $\frac{j0.2(9.6 + j2.8)}{9.6 + j3}$
= 13.6 + j1 = 13.64/4.204° Ω

The desired current is

$$\mathbf{I} = \frac{\mathbf{V}}{\mathbf{Z}} = \frac{50/0^{\circ}}{13.64/4.204^{\circ}} = 3.666/-4.204^{\circ} \,\mathrm{A}$$