

Microwave Engineering ETE 415

LECTURE 2 TRANSMISSION-LINE THEORY-I

T-Line Theory

T-Lines are used in countless ways in modern socity

- Communications
- Electronics circuits/ Computers
- Power distribution
- Photonics



Co-planar



USB 3.0 Shielded Cable





Why T-Lines?-I

Consider two ICs being connected by conducting traces on PCB.



When the voltage at 1 changes state, does that new voltage appear at 2 Instantaneously ?



This propagation of voltage signals is modeled as a "T-line".

We will see that voltage and current can propagate along a T-Line as <u>waves</u>! Fantastic.

T-Line Theory

• Lumped circuits: resistors, capacitors, inductors

Neglects time delays (phase change)

• Distributed circuit elements: T-lines

Account for propagation and time delays (phase change)



We need T-line theory whenever the length of a line is significant compared to a wavelength.

TEM T-Lines

- All true TLs share one common characteristic: the *E* and *H* fields are all \perp the direction of propagation.
- These are called **TEM fields** for **t**ransverse **e**lectric and **m**agnetic fields.



T-Line Model (RLGC Model)

- There is **conduction current** in the two conductors and a **displacement curren** between these two conductors where the electric field *E* is varying with time.
- Conduction current impedance effects:
 - R' [Ω /m], series resistance due to losses in the conductors,
 - L' [H/m], series inductance due to the current flow in the conductors and the magnetic flux linking the current path.
- Displacement current impedance effects:
 - G' [S/m], shunt conductance due to losses in the dielectric between the conductors,
 - C' [F/m], shunt capacitance due to the time varying electric field between the two conductors.

Note: R' and G', represent loss.





Analysis of T-Lines

On a T-Line, the voltage and current vary along the structure in time *t* and spatially in the *z* direction \Rightarrow they are expressed as i(z, t), and v(z, t), respectively

 $(z + \Delta z, t)$

How do we solve for v(z, t) and i(z, t)?

We first need to develop the governing equations for the voltage and current, and then solve these equations.

T-Line Equations-I



To develop the governing equation for v(z, t), apply KVL: $(z, t) = v(z + \Delta z, t) + i(z, t)R'\Delta z + L'\Delta z \frac{\partial i(z, t)}{\partial t}$ (1a) $\Delta v = v(z + \Delta z, t) - v(z, t) = -i(z, t)R'\Delta z - L'\Delta z \frac{\partial i(z, t)}{\partial t}$ Similarly, for the current i(z, t) apply KCL at the node A: $(z, t) = i(z + \Delta z, t) + i(z + \Delta z, t)G'\Delta z + C'\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t}$ (1b) $\Delta i = i(z + \Delta z, t) - i(z, t) = -v(z + \Delta z, t)G'\Delta z - C'\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t}$



In the limit as $\Delta z \rightarrow 0$, the term on the LHS in (2) and (3) is the forward difference definition of derivative. Hence,

$$\begin{aligned} \frac{\partial v(z,t)}{\partial z} &= -R'i(z,t) - L'\frac{\partial i(z,t)}{\partial t} \\ \frac{\partial i(z,t)}{\partial z} &= -G'v(z,t) - C'\frac{\partial v(z,t)}{\partial t} \end{aligned}$$

coupled partial differential equations

(4)

5

Eqs. (4) and (5) are called the telegrapher equations or the T-Line equations.

T-Line Wave Equations-I

- Now combine (4) and (5) to form two equations, each a function of *v* or *i* only.
 Switch the
- To do this, take $\frac{\partial}{\partial}$ of Eq. (4) $\left(\frac{\partial v}{\partial z} = -R'i L'\frac{\partial i}{\partial t}\right)$: order of the $\frac{\partial^2 v}{\partial z^2} = -R'\frac{\partial i}{\partial z} - L'\frac{\partial}{\partial z}\left(\frac{\partial i}{\partial t}\right) = -R'\frac{\partial i}{\partial z} - L'\frac{\partial}{\partial t}\left(\frac{\partial i}{\partial z}\right)$ Substituting from Eq. (5) $\left(\frac{\partial i}{\partial z} = -G'v - C'\frac{\partial v}{\partial t}\right)$: $\frac{\partial^2 v}{\partial z^2} = -R'\left[-G'v - C'\frac{\partial v}{\partial t}\right] - L'\left[-G'\frac{\partial v}{\partial t} - C'\frac{\partial^2 v}{\partial t^2}\right]$

 $- - (R'G')i - (R'C' + L'G') \stackrel{\circ}{=} - L'C' \stackrel{\circ}{=}$

The same equation also holds for *i*.



 $\Rightarrow \alpha \ge 0$ is the attenuation constant and $\beta \ge 0$ is the phase constant.



Voltage Wave Equation Solutions **Backward** travelling wave (a wave traveling in the -z direction): $V_{-}(z) = V_{-}e^{+\gamma z} = V_{-}e^{+\gamma z}e^{+j/z}$

Converting back to the time domain

$$\begin{aligned} \boldsymbol{v}^{-}(\boldsymbol{z},\boldsymbol{t}) &= \Re \left\{ \left(V_{o}^{-}e^{\alpha z}e^{j\beta z} \right)e^{jwt} \right\} \\ &= \Re \left\{ \left(|V_{o}^{-}|e^{j\phi^{-}}e^{\alpha z}e^{j\beta z} \right)e^{jwt} \right\} \\ &= |V_{o}^{-}|e^{+\alpha z}\cos(wt+\beta z+\phi^{-}) \end{aligned}$$

♦ where \$\phi^-\$ is the phase angle of the complex voltage \$V_o^-\$
Some complete time domain solution:
If \$\left(z) e^{jwt}\$
= \$\left(V(z)e^{jwt}\$)
= \$\left(V_o^+)e^{-\alpha z}\cos(wt - \beta z + \phi^+) + |V_o^-|e^{+\alpha z}\cos(wt + \beta z + \phi^-)\$
If \$\left(z,t) = \$\left(\begin{bmatrix}{l} e^{-tx} \cos(wt - \beta z + \phi^+) + |V_o^-|e^{+\alpha z} \cos(wt + \beta z + \phi^-)\$
If \$\left(z,t) = \$\left(\begin{bmatrix}{l} e^{-tx} \cos(wt - \beta z + \phi^+) + |V_o^-|e^{+\alpha z} \cos(wt + \beta z + \phi^-)\$
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If \$\left(z,t) = \$\begin{bmatrix}{l} e^{-tx} \cos(wt - \beta z + \phi^+) + |V_o^-|e^{+tx} \cos(wt + \beta z + \phi^-)\$
If \$\left(z,t) = \$\begin{bmatrix}{l} e^{-tx} \cos(wt - \phi^+) + |V_o^-|e^{-tx} \cos(wt - \phi^+) + \phi^-]\$

Attenuation Constant (α)

- **The attenuation constant** α **[Np/m]:** decreases the amplitude of the voltage and current wave along the T-Line.
- For +ve traveling wave:



Wavelength (λ_g)

The wavelength, λ_g :- the distance between two successive maxima (or minima, or any other reference points) on the wave at a fixed instant of time.





Phase Velocity (v_p)

Solution Phase velocity v_p : velocity at which a fixed phase point on the wave travels.





Consider "riding" one part of the wave
 $wt - \beta z = \text{constant} (\text{choose } 0) \Rightarrow z = \frac{wt}{\beta}$ Phase velocity calculation
 dz = d(wt) = w





At t = 1 s, focus on the peak located at z = 1.5 m

$$\implies S_{+} = t - \frac{z}{v_{p}} = 1 - \frac{1.5}{1} = -0.5$$

The argument S_+ stays constant for varying $t \& z \Longrightarrow at t = 2 s$, for example:

$$S_{+} = -0.5 = t - \frac{z}{v_{p}} = 2 - \frac{z}{1} \implies z = 2.5 \text{ m.}$$

So, the peak has now moved to position z = 2.5 m at t = 2 s. Likewise, every point on this function moves the same distance (1 m) in this time (1 s). \Rightarrow This is called **wave motion**. The speed of this movement is: $\frac{\Delta z}{m} = \frac{1}{m} = 1 \text{ m s} = v_p$



Z_0 for Backward-Traveling Wave

A wave is traveling in the -z direction.

SO

Note: The reference directions for voltage and current are the same as <u>for the forward wave.</u>



 \mathcal{Z}



50 Ohm T-Lines!!

In most RF systems, $Z_0 = 50 \Omega$ WHY???



Solution If the medium between the two conductors is homogeneous (uniform) and is characterized by (μ , ε), then we have that:

- 119 ->

it is always the speed of light (in the material).

Generality of T-Line Theory



Terminated T-Line-I



Terminating impedance (load)

 Z_L

 Z_0, γ

Where do we assign z = 0? • For mathematical convenience, the usual choice is at the load, i.e., z = 0.



Note: The length ℓ measures distance from the load: $\ell = -z$

Terminated T-Line-II

The "lumped load" Z_L that terminates the TL is considered a **boundary condition** for the voltage and current:

 $V(z=0) = I(z=0)Z_L \quad \Rightarrow \quad Z_L = -$

Apply this boundary condition as:

 $V(z=0) = V_{o}^{+} + V_{o}^{-}$

 $\frac{V(0)}{V(0)} = \frac{V_o^+ + V_o^-}{V_o^+ - Z_0} = \frac{V_o^- + V_o^-}{V_o^+ - Z_0} = \frac{V_o^- + V_o^-}{V_o^- - Z_0} = \frac{V_o^- + V_o^-}{V_o^- - Z_0} = \frac{V_o^- + V_o^-}{V_o^- - Z_0} = \frac{V_o^- + V_o^- + V_o^-}{V_o^- - Z_0} = \frac{V_o^- + V_o^-}{V_o^- - Z_0} = \frac{V_$





Solving for V_0^-/V_0^+ , and defining this ratio as the voltage reflection coefficient at the load (z = 0), we find

complex number $\Gamma_{L} \equiv \frac{V_{o}^{-}}{V_{o}^{+}} = \frac{Z_{L} - Z_{0}}{Z_{L} + Z_{0}}$



Zin of a T-Line-I

Terminating impedance (load)

 Z_L

 $\ell \equiv$ distance away from load

 $V(z) = V^{+}e^{-\gamma z} + V^{-}e^{+\gamma z}$

$$\begin{aligned} \mathbf{C}(-\mathbf{\ell}) &= V_o^+ e^{+\gamma\ell} + V_o^- e^{-\gamma\ell} \\ &= V_0^+ e^{+\gamma\ell} \left(1 + \frac{V_0^-}{V_0^+} e^{-2\gamma\ell} \right) \\ &= V_0^+ e^{+\gamma\ell} \left(1 + \Gamma_L e^{-2\gamma\ell} \right) \end{aligned}$$

Similarly, the current at $z = -\ell$

Input impedance seen "looking" towards load at $z = -\ell$. $Z_{in} = Z(-\ell) \equiv V(-\ell)$ $I(-\ell)$ $I(-\ell)$ $I + \Gamma_L e^{-2\gamma\ell}$ Z(0) = ?



Zin of a T-Line-III

 $\cosh x = \frac{1}{2} (e^x + e^{-x})$ and $\sinh x = \frac{1}{2} (e^x - e^{-x})$

Using trigonometric identities:

Mence, we have $Z(-\ell) = Z_0 \frac{Z_L \cosh(\gamma \ell) + Z_0 \sinh(\gamma \ell)}{Z_0 \cosh(\gamma \ell) + Z_L \sinh(\gamma \ell)}$

M Divide both the numerator and the denominator by $cosh(\gamma \ell)$

$$Z_{\rm in} = Z(-\ell) = Z_0 \frac{Z_L + Z_0 \tanh(\gamma \ell)}{Z_0 + Z_L \tanh(\gamma \ell)}$$





Matched Load $(Z_L = Z_0)$



 $Z_{
m in} = Z_0 \quad [\Omega]$

The input impedance is Z_0 regardless of the length of the TL.





Using TLs to Synthesize Elements

We can obtain any reactance that we want from a short or open TL.

This is very useful is microwave engineering.





A microwave filter constructed from microstrip.

Thank you Very Much !!!