

COMPUTER GRAPHICS CURVES

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In computer graphics, we often need to draw different types of objects onto the screen. Objects are not flat all the time and we need to draw curves many times to draw an object.

Types of Curves

A curve is an infinitely large set of points. Each point has two neighbors except endpoints. Curves can be broadly classified into three categories – **explicit**, **implicit**, and **parametric curves**.

Implicit Curves

Implicit curve representations define the set of points on a curve by employing a procedure that can test to see if a point is on the curve. Usually, an implicit curve is defined by an implicit function of the form –

$$f(x, y) = 0$$

It can represent multivalued curves *multipleyvaluesforanxvalue*. A common example is the circle, whose implicit representation is

$$x^2 + y^2 - R^2 = 0$$

Explicit Curves

A mathematical function $y = f(x)$ can be plotted as a curve. Such a function is the explicit representation of the curve. The explicit representation is not general, since it cannot represent vertical lines and is also single-valued. For each value of x , only a single value of y is normally computed by the function.

Parametric Curves

Curves having parametric form are called parametric curves. The explicit and implicit curve representations can be used only when the function is known. In practice the parametric curves are used. A two-dimensional parametric curve has the following form –

$$P(t) = (f(t), g(t)) \text{ or } P(t) = (x(t), y(t))$$

The functions f and g become the x, y coordinates of any point on the curve, and the points are obtained when the parameter t is varied over a certain interval $[a, b]$, normally $[0, 1]$.

Bezier Curves

Bezier curve is discovered by the French engineer **Pierre Bézier**. These curves can be generated under the control of other points. Approximate tangents by using control points are used to generate curve. The Bezier curve can be represented mathematically as –

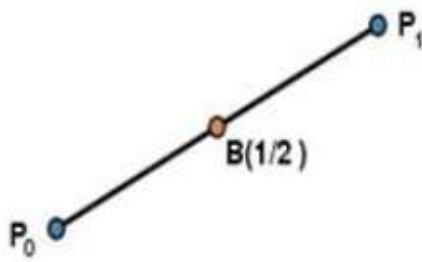
$$\sum_{k=0}^n P_k B_k^n(t)$$

Where p_i is the set of points and $B_i^n(t)$ represents the Bernstein polynomials which are given by –

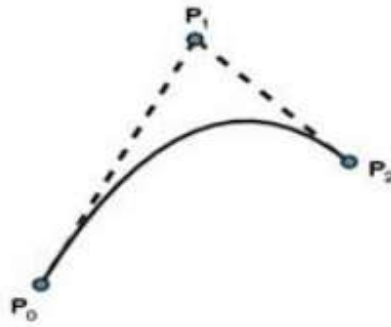
$$B_i^n(t) = \binom{n}{i} (1-t)^{n-i} t^i$$

Where n is the polynomial degree, i is the index, and t is the variable.

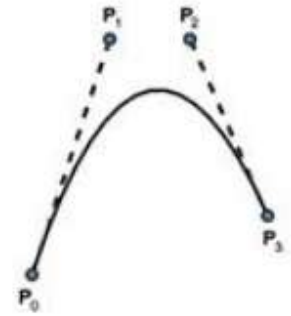
The simplest Bézier curve is the straight line from the point P_0 to P_1 . A quadratic Bezier curve is determined by three control points. A cubic Bezier curve is determined by four control points.



Simple Bezier Curve



Quadratic Bezier Curve



Cubic Bezier Curve

Properties of Bezier Curves

Bezier curves have the following properties –

- They generally follow the shape of the control polygon, which consists of the segments joining the control points.
- They always pass through the first and last control points.
- They are contained in the convex hull of their defining control points.
- The degree of the polynomial defining the curve segment is one less than the number of defining polygon points. Therefore, for 4 control points, the degree of the polynomial is 3, i.e. cubic polynomial.
- A Bezier curve generally follows the shape of the defining polygon.
- The direction of the tangent vector at the end points is same as that of the vector determined by first and last segments.
- The convex hull property for a Bezier curve ensures that the polynomial smoothly follows the control points.
- No straight line intersects a Bezier curve more times than it intersects its control polygon.
- They are invariant under an affine transformation.
- Bezier curves exhibit global control means moving a control point alters the shape of the whole curve.
- A given Bezier curve can be subdivided at a point $t=t_0$ into two Bezier segments which join together at the point corresponding to the parameter value $t=t_0$.

B-Spline Curves

The Bezier-curve produced by the Bernstein basis function has limited flexibility.

- First, the number of specified polygon vertices fixes the order of the resulting polynomial which defines the curve.
- The second limiting characteristic is that the value of the blending function is nonzero for all parameter values over the entire curve.

The B-spline basis contains the Bernstein basis as the special case. The B-spline basis is non-global.

A B-spline curve is defined as a linear combination of control points P_i and B-spline basis function $N_{i,k}$ given by

$$C(t) = \sum_{i=0}^n P_i N_{i,k}(t), \quad n \geq k - 1, \quad t \in [tk - 1, tk + 1]$$

Where,

- $\{p_i; i=0, 1, 2, \dots, n\}$ are the control points
- k is the order of the polynomial segments of the B-spline curve. Order k means that the curve is made up of piecewise polynomial segments of degree $k - 1$,
- the $N_{i,k}(t)$ are the “normalized B-spline blending functions”. They are described by the order k and by a non-decreasing sequence of real numbers normally called the “knot sequence”.

$$t_i; i = 0, \dots, n + K$$

The $N_{i,k}$ functions are described as follows –

$$N_{i,1}(t) = \begin{cases} 1, & \text{if } t \in [t_i, t_{i+1}) \\ 0, & \text{Otherwise} \end{cases}$$

and if $k > 1$,

$$N_{i,k}(t) = \frac{t - t_i}{t_{i+k} - t_i} N_{i,k-1}(t) + \frac{t_{i+1} - t}{t_{i+1} - t_{i+2}} N_{i+1,k-1}(t)$$

and

$$t \in [t_{k-1}, t_{n+1})$$

Properties of B-spline Curve

B-spline curves have the following properties –

- The sum of the B-spline basis functions for any parameter value is 1.
- Each basis function is positive or zero for all parameter values.
- Each basis function has precisely one maximum value, except for $k=1$.
- The maximum order of the curve is equal to the number of vertices of defining polygon.
- The degree of B-spline polynomial is independent on the number of vertices of defining polygon.
- B-spline allows the local control over the curve surface because each vertex affects the shape of a curve only over a range of parameter values where its associated basis function is nonzero.
- The curve exhibits the variation diminishing property.
- The curve generally follows the shape of defining polygon.
- Any affine transformation can be applied to the curve by applying it to the vertices of defining polygon.
- The curve lies within the convex hull of its defining polygon.